# GEOMETRY OF A SYSTEM OF LINEAR HOMOGENEOUS PARTIAL DIFFERENTIAL EQUATIONS 

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## Introduction

Using a system of partial differential equations, in this paper we shall study a configuration of surfaces and congruences of lines whose elements are in a $1-1$ correspo idence. Many eminent geometers such as Wilczynski, Lane and Green had investigated the properties of a single congruence of lines but very few have studied a pair of congruences.

In this work we shall consider a pair of congruences whose generators are in 1-1 correspondence and which are related in a special way. We shall make use of the properties of integrable systems of differential equations and the theory of transformation to explore the intrinsic nature of the new configuration.

## The Elements of the Theory of Surfaces

The concept of surface is basic in this study. Roughly speaking, a surface is a two-parameter family of points; that is, it is the locus of a point moving with two degrees of freedom. For the purposes of this study, however, these descriptions are not altogether adequate. We shall need more precise definitions.

Let the homogeneous projective coordinates ( $\mathrm{x}_{1}, \mathrm{x}_{2}, \mathrm{x}_{3}, \mathrm{x}_{4}$ ) of a point in a three dimensional space be given as single-valued analytic functions of two independent variables $u$ and $v$ by

$$
x_{i}=x_{i}(u, v), i=1,2,3,4,
$$

which we write in vector notation as:

$$
x=x(u, v) .
$$

## Curves on a Surface

As $u$ and $v$ vary in a domain $T$ the point generates a surface an analytic surface. The point shall be denoted by $\mathrm{P}_{\mathrm{x}}$ and its locus by $\mathrm{S}_{\mathrm{x}}$.

A curve is a one parameter family of points. If we put $\mathrm{v}=$ constant, $c$, in the parametric vector equation $x=x(u, v)$ of $S_{x}$ we get a one-parameter set of points whose vector equation is

$$
x=x(u, c)=f(u) .
$$

The locus of the point $P_{x}$ is a curve which we shall call a $u$ -curve on the surface $\mathrm{S}_{\mathrm{x}}$. If c varies over all possible values we obtain a family of u-curves which covers $S_{\mathbf{x}}$.

A second family of curves is obtained if we set $u=$ constant $=$ c. It is the locus of $\mathrm{P}_{\mathbf{x}}$ where
$\mathrm{x}=\mathrm{x}(\mathrm{c}, \mathrm{v})=\mathrm{g}(\mathrm{v})$.
If c takes all possible values a second family of curves - the v -curves - is obtained.

The surface $S_{x}$ is then covered by two families of curves the $u$-curves and the v-curves. Thru each point $P_{x}$ intersect one $u$-curve and one v-curve. The parameters $u$ and $v$ are called the curvillinear coordinates of $\mathrm{P}_{\mathbf{x}}$.

Let $C$ be any curve on the surface $S_{x}$. Then it is a one parameter family of points. Therefore, each of the coordinates $u$ and $v$ of a point on $c$ is expressible as a function of a parameter $t$; that is,

$$
\mathrm{u}=\mathrm{u}(\mathrm{t}), \mathrm{v}=\mathrm{v}(\mathrm{t}) .
$$

Thus C is the locus of points $\mathrm{P}_{\mathbf{x}}$, where

$$
\mathrm{x}=\mathrm{x}(\mathrm{u}(\mathrm{t}), \mathrm{v}(\mathrm{t})),
$$

as $t$ varies over all possible values.
Consider a point $P_{x}$ on $C$ with coordinates $u(t), v(t)$. The line $P_{x} P_{x}{ }^{\prime}$, where $x=x(u(t), v(t))$ and $x^{\prime}=\frac{\partial x}{\partial u} \frac{d u}{d t}+\frac{\partial x}{\partial v} \frac{d v}{d t}$ is tangent to $C$ at point $P_{x}$.

In the case of the $u$-curve and the $v$-curve the lines $P_{\mathbf{x}} \mathrm{P}_{\mathbf{x}_{u}}$ and $P_{x} P_{x_{v}}$ are tangent lines to these curves respectively at $P_{x}$.

A differential equation of the form

$$
M(u, v) d u+N(u, v) d v=0
$$

represents a one-parameter family of curves on the surface. For, if

$$
\mathrm{v}=\mathrm{f}(\mathrm{u}, \mathrm{c}), \mathrm{c} \text { is a variable parameter, }
$$

is a general solution of the differential equation, from the vector equation $x=x(u, v)$ of $S_{x}$, we get, when $v$ is replaced by $f(u, c)$, the vector equation

$$
\mathrm{x}=\mathrm{x}(\mathrm{u}, \mathrm{f}(\mathrm{c}))=\mathrm{g}(\mathrm{u}, \mathrm{c}),
$$

which is the vector equation of a one-parameter family of curves © $\mathrm{n}_{\mathrm{S}}$.

In particular, the parametric curves $\mathrm{u}=$ constant and $\mathrm{v}=$ constant are integrals of $d u=0$ and $d v=0$ or of dudv $=0$.

## Tangent Plane and Osculating Plane

The plane determined by the points $\mathrm{P}_{\mathbf{x}}, \mathrm{P}_{\mathbf{x}_{\mathrm{u}}}$ and $\mathrm{P}_{\mathbf{x}_{\mathrm{v}}}$ is called the tangent plane of $S_{x}$ at $P_{x}$.

If $C$ is a curve on $S_{x}$ thru $P_{x}$ defined by

$$
\mathrm{u}=\mathrm{u}(\mathrm{t}), \mathrm{v}=\mathrm{v}(\mathrm{t}),
$$

then the plane determined by $\mathrm{P}_{\mathrm{x}}, \mathrm{P}_{\mathbf{x}}{ }^{\prime}$ and $\mathrm{P}_{\mathrm{x}}{ }^{\prime \prime}$, where

$$
\begin{aligned}
x^{\prime}= & x_{u} \frac{d u}{d t}+x_{v} \frac{d v}{d t} \\
x^{\prime \prime}= & x_{u u} \frac{d y^{2}}{d t}+2 x_{u v} \frac{d u}{d t} \frac{d v}{d t}+x_{v v} \frac{d v^{2}}{d t}+ \\
& x_{u} \frac{d^{2} u}{d t^{2}}+x_{v} \frac{d^{2} v}{d t^{2}},
\end{aligned}
$$

is called the osculating plane of $C$ at $P_{x}$.
If at each point $P_{x}$ of $C$ on $S_{x}$, the tangent plane of $S_{x}$ and the osculating plane of C coincide, then C is an asymptotic curve on $\mathrm{S}_{\mathbf{x}}$.

If $\overline{\mathbb{X}}$ is any point in the tangent plane of $S_{x}$ or in the osculating plane of $C$ at $P_{x}$ then

$$
\begin{align*}
& \left(\underline{\bar{x}}, x, x_{u}, x_{v}\right)=0 \\
& \left(\underline{\bar{X}}, x, x^{\prime}, x^{\prime \prime}\right)=0 \tag{2.2}
\end{align*}
$$

are the equations of the tangent plane of $\mathrm{S}_{\mathrm{x}}$ and the osculating plane of $C$ respectively at $P_{x}$.

We say that a curve C on a surface $\mathrm{S}_{\mathrm{x}}$ is an asymptotic curve if the tangent plane of $S_{x}$ at each point of $C$ coincides with the osculating plane of $C$.

Since $\mathrm{P}_{\mathrm{x}}$ and $\mathrm{P}_{\mathrm{x}}{ }^{\prime}$ are points in both the planes in (2.2), a necessary and sufficient condition that C is an asymptotic curve is that the point $\mathrm{P}_{\mathrm{x}}{ }^{\prime \prime}$ also lies in the tangent plane.

This means that

$$
\left(x^{\prime \prime} \mathrm{x}_{\mathrm{x}}^{\mathrm{u}} \mathrm{x}_{\mathrm{v}}\right)=0 .
$$

When the value of $\mathrm{x}^{\prime \prime}$ given by (2.1) is substituted in this equation we get

$$
L d u^{2}+2 M d u d v+N d v^{2}=0
$$

where

$$
\begin{align*}
& L=\left(x_{u v}, x, x_{u}, x_{v}\right) \\
& M=\left(x_{u v}, x, x_{u}, x_{v}\right) \\
& N=\left(x_{u v}, x, x_{u}, x_{v}\right) .
\end{align*}
$$

The differential equation of the parametric net on $S_{x}$

$$
d u d v=0
$$

This equation will coincide with (2.3) if, and only if

$$
\mathrm{L}=0, \mathrm{M} \neq 0, \mathrm{~N}=0
$$

that is if, and only if

$$
\begin{aligned}
& \left(x_{u u}, x, \quad x_{u}, x_{v}\right)=0 \\
& \left(x_{\mathrm{vv}}, x, x_{u}, x_{v}\right)=0 \\
& \left(x_{u v}, x, x_{u}, x_{v}\right) \neq 0 .
\end{aligned}
$$

The first and second equation say that $\mathrm{x}_{\mathrm{uu}}$ and $\mathrm{x}_{\mathrm{vv}}$ are linear combinations of $x, x_{u}$ and $x_{v}$, whereas the last relation says that $x_{u v}$ is linearly independent of $x, x_{u}$ and $x_{v}$. Hence we have proved that the parametric curves on $S_{x}$ are asymptotics on $S_{x}$ if, and only if there exist scalar functions $p(u, v), q(u, v), \alpha(u, v), \beta(u, v), \gamma(u, v)$ and $\delta(u, v)$ such that

$$
\begin{align*}
& \mathrm{x}_{\mathrm{u} u}=\mathrm{p} \mathrm{x}+\alpha \mathrm{x}_{\mathrm{u}}+\beta \mathrm{x}_{\mathrm{v}}  \tag{2.5}\\
& \mathrm{x}_{\mathrm{vv}}=\mathrm{qx}+\gamma \mathrm{x}_{\mathrm{u}}+\delta \mathrm{x}_{\mathrm{v}}
\end{align*}
$$

and no relation of the form

$$
P x_{u v}+Q x_{u}+R x_{v}+S_{x}=O
$$

where $P, Q, R$ and $S$ are scalar functions of $u$ and $v$, exists.

Thus we have shown that a surface $S_{x}$ is an integral surface of a system (2.5) of second order partial differentiations when the parametric curves are the asymptotic curves on the surface. But it is not true conversely that given a system (2.5) there exists an integral surface $S_{x}$. For the existence of $S_{x}$ satisfying (2.5), the system (2.5) must have to be completely integrable. The coefficients $\mathrm{p}, \mathrm{q}, \alpha, \hat{\beta}, \gamma, \delta$ cannot be arbitrary. They must satisfy certain conditions for integrability. These conditions arise from the demand that

$$
\left(\mathrm{x}_{\mathrm{uu}}\right)_{\mathrm{uv}}=\left(\mathrm{x}_{\mathrm{uu}}\right)_{\mathrm{vu}},\left(\mathrm{v}_{\mathrm{uu}}\right)_{\mathrm{vv}}=\left(\mathrm{x}_{\mathrm{vv}}\right)_{\mathrm{uu}},\left(\mathrm{x}_{\mathrm{vv}}\right)_{\mathrm{uv}}=\left(\mathrm{x}_{\mathrm{vv}}\right)_{\mathrm{vu}} .
$$

Lane proved that $S_{x}$ is an integral of the system

$$
\begin{align*}
& \mathbf{x}_{\mathrm{uu}}=\mathrm{px}+\theta_{\mathrm{u}} \mathrm{x}_{\mathrm{u}}+\beta_{\mathrm{xv}} \\
& \mathbf{x}_{\mathrm{w}}=\mathrm{qx}+\gamma \mathrm{x}_{\mathrm{u}}+\theta_{\mathrm{v}} \mathrm{x}_{\mathrm{v}} \tag{2.6}
\end{align*}
$$

provided the following integrability conditions are satisfied:

$$
\begin{aligned}
& \theta_{u v v}=(\varphi \gamma)_{u}+2 q_{u}+\theta_{v} \theta_{u v}-\beta \gamma \psi \\
& \theta_{u u v}=(\varphi \beta)_{v}+2 p_{v}+\theta_{u} \theta_{u v}-\beta \gamma \varphi \\
& p_{v v}-\theta_{v} p_{v}+\beta q_{v}+2 q \beta_{v}=q u \bar{u} \theta_{u} q_{u}+\gamma p_{u}+2 p \gamma_{u}
\end{aligned}
$$

where

$$
\begin{equation*}
\varphi=\left(\log \beta \gamma^{2}\right)_{\mathrm{u}}, \quad \psi=\left(\log \beta^{2} \gamma\right)_{\mathrm{v}} \tag{2.8}
\end{equation*}
$$

When the integrability conditions (2.7) are satisfied by the coefficients of (2.6), the system is completely integrable and has four independent solutions:

$$
x_{i}=x_{i}(u, v), i=1,2,3,4
$$

which are then the coordinates of a variable point $P_{x}$ the locus of which is a surface $\mathrm{S}_{\mathbf{x}}$.

Thus the systems (2.6) and (2.7) are differential defining an analytic surface $S_{x}$ referred to its asymptotic net.

A second net of curves on the surface to which $\mathrm{S}_{\mathrm{x}}$ may be referred is a conjugate net. In a conjugate net, the tangents of the
(1) E. P. Lane, Projective Differential Geometry of Curves and Surface, University of Chicago Press, 1932 p. 69. This book will be referred to as Lane.
curves of one family at the points of each fixed curve of the other family form a developable. If the conjugate net is taken as the reference curves on the surface $S_{x}$, then $S_{x}$ is an integral of a system of the form

$$
\begin{align*}
& x_{u u}=a x_{v v}+b x_{u}+c x_{v}+d x  \tag{1}\\
& x_{u v}=b^{\prime} x_{u}+c^{\prime} x_{v}+d^{\prime} \mathbf{x},
\end{align*}
$$

with the corresponding integrability conditions.

## Congruences of Lines

A congruence of lines is a two-parameter family of lines. It is the locus of a line moving with two degrees of freedom. A congruence may be formed in several ways. For our purposes, we shall consider congruence whose generators are in 1-1 correspondence with the points of a surface.

Let $S_{x}$ and $S_{y}$ be two analytic surfaces whose points are in $1-1$ correspondence. Then the points $\mathrm{P}_{\mathrm{x}}$ on $\mathrm{S}_{\mathrm{x}}$ and $\mathrm{P}_{\mathrm{y}}$ on $\mathrm{S}_{\mathrm{y}}$ correspond if they have the same curvillinear coordinates ( $u, v$ ). The line $\mathrm{P}_{\mathrm{x}} \mathrm{P}_{\mathrm{y}}$ generates a congruence as $\mathrm{P}_{\mathrm{x}}$ and $\mathrm{P}_{\mathrm{y}}$ vary independently over $S_{x}$ and $S_{y}$ respectively, since each line $P_{\mathbf{x}} P_{\mathbf{y}}$ is determined by two independent parameters $u$ and $v$.

Consider now two congruences $\Gamma_{\mathbf{x y}}=\left(\mathrm{P}_{\mathbf{x}} \mathrm{P}_{\mathrm{y}}\right)$ and $\Gamma_{\overline{\mathrm{z}} \mathrm{y}}=$ ( $\mathrm{P}_{\underline{\underline{x}}} \mathrm{P}_{\mathrm{y}}$ ) determined by the pairs ( $\mathrm{S}_{\mathrm{x}}, \mathrm{S}_{\mathrm{y}}$ ) and ( $\mathrm{S}_{\underline{\underline{\underline{x}}}}, \mathrm{~S}_{\mathrm{y}}$ ) of surfaces, whose points are in a 1-1 correspondence; that is, the points $\mathrm{P}_{\mathrm{x}}$, $P_{y}, P_{\overline{\underline{x}}}$ and $P_{y}$ have the same curvillinear coordinates ( $u, v$ ). Then the generator $\mathrm{P}_{\dot{x}} \mathrm{P}_{\dot{y}}$ of $\Gamma_{\mathbf{x y}}$ and the generator $\mathrm{P}_{\underline{\bar{x}}} \mathrm{P}_{\underline{y}}$ of $\Gamma_{\underline{\bar{x}} \underline{y}}$ are corresponding generators of $\Gamma_{\mathbf{x y}}$ and $\Gamma_{\overline{\mathbf{x}} \mathrm{y}}$.

The aim of this paper is to study this congruence correspondence. We shall start by setting up a system of partial differential equations for the congruences $\Gamma_{\mathbf{x y}}$ and $\Gamma_{\bar{x} \underline{y}}$ and deduce therefrom the properties of the new geometric configuration.

We shall assume that $\mathrm{P}_{\mathrm{y}}$ does not lie in the tangent plane of $S_{x}$ at $P_{x}$. Then $\left(x, x_{u}, x_{v}, y\right) \neq 0$. Therefore, if $\alpha$ and $\beta$ are any vector function of $u$ and $v$, there exist scalar functions $A, B, C$, $D, A^{\prime}, G^{\prime}, D^{\prime}$, of $u$ and $v$ such that

$$
\begin{aligned}
& \alpha=A x+B y+C x_{u}+D x_{v} \\
& \beta=A^{\prime} x+B^{\prime} y+C^{\prime} x_{u}+D x_{v} .
\end{aligned}
$$

[^0]Eliminating $\mathrm{x}_{\mathrm{u}}$ and $\mathrm{x}_{\mathrm{v}}$ in succession, we have:

$$
\begin{aligned}
& \frac{\mathrm{D}^{\prime} \alpha-\mathrm{D} \beta}{\mathrm{CD}^{\prime}-\mathrm{c}^{\prime} \mathrm{D}}=\frac{\mathrm{AD}^{\prime}-\mathrm{A}^{\prime} \mathrm{D}}{\mathrm{CD}^{\prime}-\mathrm{C}^{\prime} \mathrm{D}} \mathrm{x}+\frac{\mathrm{BD}^{\prime}-\mathrm{B}^{\prime} \mathrm{D}}{\mathrm{CD}^{\prime}-\mathrm{C}^{\circ} \mathrm{D}} \mathrm{y}+\mathrm{x}_{\mathrm{u}} \\
& \frac{C^{\prime} \alpha-c \beta}{C^{\prime} D-c^{\prime} D^{\prime}}=\frac{\mathrm{Ac}^{\prime}-\mathrm{A}^{\prime} C}{\mathrm{C}^{\prime} \mathrm{D}-\mathrm{cD}^{\prime}} \mathrm{x}+\frac{\mathrm{BC}^{\prime}-\mathrm{B}^{\prime} \mathrm{C}}{\mathrm{C}^{\prime} \mathrm{D}-\mathrm{c}} \mathrm{y}+\mathrm{x}_{\mathrm{v}} \text {, } \\
& \mathrm{CD}^{\prime}-\mathrm{C}^{\prime} \mathrm{D} \neq 0 .
\end{aligned}
$$

Then if we put

$$
\underline{\mathrm{X}}=\frac{\mathrm{D}^{\prime} \alpha-\mathrm{D} \beta}{\mathrm{CD}^{\prime}-\mathrm{C}^{\prime} \mathrm{D}}, \underline{\mathrm{Y}}=\frac{\mathrm{C}^{\prime} \alpha-\mathrm{c} \beta}{\mathrm{CD}^{\prime}-\mathrm{C}^{\prime} \mathrm{D}}
$$

we can write the above equations in the form

$$
\begin{align*}
& \underline{\bar{x}}=x_{u}-l x-m y  \tag{3.1}\\
& \underline{Y}=x_{v}-l^{\prime} x-m^{\prime} y .
\end{align*}
$$

These define the surfaces $\mathrm{S}_{\mathrm{x}}$ and $\mathrm{S}_{\mathrm{y}}$. Note that if $\left(\mathrm{x}, \mathrm{y}, \mathrm{x}_{\mathrm{u}} \mathrm{x}_{\mathrm{v}}\right) \neq 0$ then

$$
(\underline{\bar{x}}, \mathrm{y}, \mathrm{x}, \mathrm{y}) \neq 0 .
$$

Hence every vector function may be expressed as a linear combination of $x, y, \underline{\bar{x}}$ and $y$ : Therefore, the study of a pair, of congruences whose generators are in 1-1 correspondence may be based on the following system of linear homogeneous partial differential equations:

Differential Equations for $\Gamma_{\mathbf{x y}}$ and $\Gamma_{\overline{\underline{x}} \mathbf{y}}$

$$
\begin{array}{ll}
x_{u}=l x+m y+\underline{\underline{x}} & y_{u}=a x+b y+c \overline{\underline{x}}+d \underline{y} \\
x_{v}=l^{\prime} x+n^{\prime} y+\underline{y} & y_{v}=a^{\prime} x+b^{\prime} y+c^{\prime} \overline{\underline{x}}+d^{\prime} y \\
\underline{\underline{x}}_{u}=e x+f y+\underline{x}^{\prime} \underline{\underline{x}}+h \underline{y} & y_{u}=p x+q y+r \underline{\bar{x}}+s y^{\prime}(3.2) \\
\bar{x}_{v}=e^{\prime} x+f^{\prime} y+g^{\prime} \underline{\underline{x}}+h^{\prime} y & \underline{y}_{v}=p^{\prime} x+q^{\prime} y+r^{\prime} \underline{\underline{x}}+s^{\prime} \underline{y}
\end{array}
$$

The scalar coefficients in the above equations are not arbitrary functions of $u$ and $v$ but must satisfy the following integrability conditions which are obtained by imposing the conditions $\mathrm{x}_{\mathrm{uv}}=\mathrm{x}_{\mathrm{vu}}, \mathrm{y}_{\mathrm{uv}}=\mathrm{y}_{\mathrm{vu}}$, etc.

## Integrability Conditions

$l^{\prime} u+p+m^{\prime} a=l v+e^{\prime}+m a^{\prime}$

$$
\begin{aligned}
& m_{u}^{\prime}+q+l^{\prime} m+m^{\prime} b=m_{v}+f^{\prime}+l m^{\prime}+m b^{\prime} \\
& \quad r+l^{\prime}+m^{\prime} c=g^{\prime}+m c^{\prime} \\
& \quad s+m^{\prime} d=h^{\prime}+l+m d^{\prime} \\
& a_{u}^{\prime}+a^{\prime} l+a b^{\prime}+c^{\prime} e+d^{\prime} p=a_{v}+l^{\prime}+a^{\prime} b+c e^{\prime}+d p^{\prime} \\
& b_{u}^{\prime}+a^{\prime} m+c^{\prime} f+d^{\prime} q=b_{v}+a m^{\prime}+c f^{\prime}+d q^{\prime} \\
& c_{u}^{\prime}+a^{\prime}+b^{\prime} c+c^{\prime} q+d^{\prime} r=C_{v}+b c^{\prime}+c g^{\prime}+d r^{\prime} \\
& d_{u}^{\prime}+b^{\prime} d+c^{\prime} b+d^{\prime} s=d_{v}+b d^{\prime}+c^{\prime}+d s^{\prime}+a \\
& e_{u}^{\prime}+e^{\prime} l+f^{\prime} a+g^{\prime} e+h^{\prime} p=e_{v}+e l^{\prime}+f a^{\prime}+g e^{\prime}+h p^{\prime} \\
& f_{u}^{\prime}+e^{\prime} m+f^{\prime} b+g^{\prime} f+h^{\prime} q=f_{v}+e m^{\prime}+f b^{\prime}+f g^{\prime} h g^{\prime} \\
& g_{u}^{\prime}+e^{\prime}+f^{\prime} c+h^{\prime} r=g_{v}+f c^{\prime}+h r^{\prime} \\
& h_{u}^{\prime}+f^{\prime} d+g^{\prime} h+h^{\prime} s=h_{v}+e+f d^{\prime}+g h^{\prime}+h s^{\prime} \\
& p_{u}^{\prime}+p^{\prime} l+q^{\prime} a+r^{\prime} e+s^{\prime} p=p_{v}+p l^{\prime}+q a^{\prime}+r e^{\prime}+s p^{\prime} \\
& q_{u}^{\prime}+p^{\prime} m+q^{\prime} b+r^{\prime} f+s^{\prime} q=q_{v}+p m^{\prime}+q b^{\prime}+r f^{\prime}+s q^{\prime} \\
& r_{u}^{\prime}+p^{\prime}+q^{\prime} c+r^{\prime} g+s^{\prime} r=r_{v}+q c^{\prime}+r g^{\prime}+s r^{\prime} \\
& s_{u}^{\prime}+q^{\prime} d+r^{\prime} h=s_{v}+p+q d^{\prime}+r h^{\prime}
\end{aligned}
$$

We now introduce an additional relation between $\Gamma_{\mathrm{xy}}$ and $\Gamma_{\underline{\underline{x}} \underline{y}}$.
Definition: Suppose that each generator $\mathrm{P}_{\mathbf{x}} \mathrm{P}_{\mathbf{y}}$ of $\Gamma_{\mathrm{xy}}$ intersects an infinite number of surfaces in such a way that the tangent plane of each surface at its point of intersection with $\mathrm{P}_{\mathbf{x}} \mathrm{P}_{\mathbf{y}}$ pass thru the corresponding line $\mathrm{P}_{\underline{\bar{x}}} \mathrm{P}_{\mathrm{y}}$ of $\Gamma_{\overline{\underline{x}} \underline{y}}$. Then the congruence $\Gamma_{\overline{\mathrm{x}} \mathrm{y}}$ is said to be stratifiable with $\Gamma_{\mathrm{xy}}$.

This definition is due to Fubini. ${ }^{1}$
We now raise the fundamental problem: Given a congruence $\Gamma_{\mathrm{xy}}$, can we construct a second congruence $\Gamma_{\overline{\underline{x}} \underline{y}}$ so that it shall be stratifiable with $\Gamma_{\mathrm{xy}}$ ?

To answer this question, let a surface $S_{z}$, intersect the generator $P_{x} P_{y}$ of $\Gamma_{x y}$ at $P_{z}$, where, $z=x+\lambda y$, and inquire whether the function $\lambda(u, v)$ can be determined so that the tangent plane of $S_{z}$ at $P_{z}$ will pass thru the line $P_{\underline{\bar{x}}} P_{\underline{y}}$.

Let

$$
(W, \bar{X}, \underline{Y}, \quad x+\lambda y)=0
$$

(1) M. S. Finikoff, Sur les congruences stratifiables, Circolo Matematica di Palermo, t. 53, p. 313. This paper will be referred to as Finikoff.
be a plane thru $\underline{X}, Y$ and $Z=x+\lambda y$. Then this will coincide with the tangent plane of $S_{z}$ at $P_{z}$, where $z=x+\lambda y$ if, and only if at $W$ $=x+\lambda y$, the following equations are satisfied:

$$
\begin{aligned}
& (W, \bar{X}, Y, x+\lambda y)=0 \\
& (W, \underline{X}, \underline{Y}, x+\lambda y)_{u}=0 \\
& (W, \underline{X}, \underline{Y}, x+\lambda y)_{V}=0
\end{aligned}
$$

The first equation is identically satisfied. The last reduces to

$$
\begin{aligned}
& \left(x+\lambda y, \underline{z}, y, \quad x_{u}+\lambda y_{u}+\lambda_{u} y\right)=0 \\
& \left(x+\lambda y, \underline{\underline{z}}, y, \quad x_{v}+\lambda y_{v}+\lambda_{v} y\right)=0
\end{aligned}
$$

which can be further simplified into

$$
\begin{aligned}
& (x, y, \bar{x}, y)\left[\lambda u-a \lambda^{2}-(1-b) \lambda+m\right]=0 \\
& (x, y, \bar{x}, y)\left[v-a^{\prime} \lambda^{2}-\left(1^{\prime}-b^{\prime}\right) \lambda+m^{\prime}\right]=0
\end{aligned}
$$

where the ifrst four equations for $\mathrm{x}_{\mathrm{u}}, \mathrm{x}_{\mathrm{v}}, \mathrm{y}_{\mathrm{u}}, \mathrm{y}_{\mathrm{v}}$ in (3.2) have heen used. Since $(x, y, x, y) \neq 0$, we conclude that

$$
\begin{align*}
& \left.\lambda_{u}-a \lambda^{2}-(1-b) \lambda+m=\right) 0  \tag{3.4}\\
& \lambda_{v}-a^{\prime} \lambda^{2}-\left(1^{\prime}-b^{\prime}\right) \lambda+m^{\prime}=0
\end{align*}
$$

which are completely integrable provided the following integrability conditions are satisfied:

$$
\begin{align*}
& a_{u}^{\prime}+a^{\prime}(1-b)=a_{v}+a\left(1^{\prime}-b^{\prime}\right) \\
& l_{u}^{\prime}-b_{u}^{\prime}-2 a^{\prime} m=l_{v}-b_{v}-2 a m^{\prime}  \tag{3.5}\\
& m_{u}^{\prime}+m\left(l^{\prime}-b^{\prime}\right)=m_{v}+m^{\prime}(1-b)
\end{align*}
$$

When these conditions (3.5) are satisfied, the equations (3.4) have an infinite number of solutions for $\lambda$. For each we get a surface $S_{z}, z=x+\lambda y$, whose tangent plane at $P_{z}$ passes thru the line $\mathrm{P}_{\mathrm{x}} \mathrm{P}_{\mathrm{y}}$ of the congruence $\Gamma_{\mathrm{xy}}$. In other words the generator $\mathrm{P}_{\bar{x}} \mathrm{P}_{\mathrm{y}}$ is the axis of a pencil of planes which are tangent planes of the family $\sigma=\left(S_{z}\right)$ of surfaces at their points of intersection with the generator $\mathrm{P}_{\mathrm{x}} \mathrm{P}_{\mathrm{y}}$ of $\Gamma_{\mathrm{xy}}$.

Let us note that the required congruence $\Gamma_{\bar{x} y}$ in the fundamental problem is determined by the vector fünctions $\bar{x}$ and $y$ defined in (3.1) which in turn are determined by the functions $\overline{1}, 1^{\prime}, m$ and $m^{\prime}$, which must satisfy (3.5) in order that $\Gamma_{\overline{\underline{x}} \underline{y}}$ will be stratifiable with $\Gamma_{\mathrm{xy}}$. How many such congruences $\Gamma_{\underline{x}}^{-\underline{y}}$ are there? This is answered by (3.5). Regarded as a system for the
determination of $1,1^{\prime}, m, m^{\prime}$ the system (3.5) consists of three operations in four unknowns. Hence there is an infinite solution for $1,1^{\prime}, m$ and $m^{\prime}$. Therefore there are an infinite number of congruences $\Gamma_{\overline{\mathrm{x}} \mathrm{y}}$ stratifiable with a given congruence $\Gamma_{\mathrm{xy}}$. We have proved the following theorem:
Theorem. A given congruence $\Gamma_{\mathrm{xy}}$ determines infinitely many congruences $\Gamma_{\overline{\underline{x}} \underline{y}}$ simply stratifiable with $\Gamma_{\mathbf{x y}}$.

In the next section we shall consider the conditions under which the stratifiability relation between $\Gamma_{\mathrm{xy}}$ and $\Gamma_{\overline{\mathrm{x}} \mathrm{y}}$ is symmetrical. What further conditions on the coefficients of (3.2) must be imposed so that $\Gamma_{\mathrm{xy}}$ is stratifiably with $\Gamma_{\overline{\mathrm{x}} \underline{y}}$ ? Is it possible to determine a function $\mu(\mathrm{u}, \mathrm{v})$ so that the tangent plane to $\mathrm{S}_{\mathrm{z}}$, $Z=\underline{\bar{x}}+\mu \mathrm{y}$, at $\mathrm{P}_{\mathrm{z}}$ shall pass thru the generator $\mathrm{P}_{\mathrm{x}} \mathrm{P}_{\mathrm{y}}$ ? If the answers are affirmative then $\Gamma_{\mathrm{xy}}$ and $\Gamma_{\underline{\bar{x}} \boldsymbol{y}}$ are said to be doubly stratifiable.

## Doubly Stratifiable Congruences.

To answer these questions, consider the plane determined by the points $\mathrm{P}_{\mathrm{x}}, \mathrm{P}_{\mathrm{y}}$ and $\mathrm{P}_{\mathrm{z}}$. The equation of this plane is

$$
(w, x, y, z)=0,
$$

This plane will coincide with the tangent plane to $S_{z}$ at $P_{z}$ if and only if

$$
\begin{aligned}
& (w, x, y, Z)=0 \\
& (w, x, y, Z)_{u}=0 \\
& (w, x, y, z)_{v}=0
\end{aligned}
$$

are satisfied for $\mathrm{W}=\mathrm{Z}-\underline{\underline{\mathrm{x}}}+\mu \underline{y}$. By an argument similar to what led us to equations (3.4) we obtain the system:

$$
\begin{align*}
& \mu_{\mathrm{u}}-\mathrm{r} \mu^{2}+(\mathrm{s}-\mathrm{g}) \mu+\mathrm{h}=\mathrm{c} \\
& \mu_{\mathrm{u}}-\mathrm{r}^{\prime} \mu^{2}+\left(\mathrm{s}^{\prime}-\mathrm{g}^{\prime}\right) \mu+\mathrm{h}^{\prime}=0, \tag{4.1}
\end{align*}
$$

with the following conditions for integrability:

$$
\begin{align*}
& r_{u}^{\prime}+r^{\prime}(g-s)=r_{v}+r\left(g^{\prime}-s^{\prime}\right)  \tag{4.2}\\
& g_{u}^{\prime}-s_{u}^{\prime}-2 r^{\prime} h=g_{v}-s_{v}-2 r h^{\prime} \\
& h_{u}^{\prime}+h\left(g^{\prime}-s^{\prime}\right)=h_{v}+h^{\prime}(g-s)
\end{align*}
$$

When these conditions are satisfied then (4.1) has an infinite number of solutions for $\mu(\mathrm{u}, \mathrm{v})$. Therefore there are infinite number of surfaces $S_{z}$, where $Z=\underline{\bar{x}}+\mu \underline{y}$. The totality of these surfaces will be denoted by $\Sigma=\left[S_{z}\right]$.

We now apply the foregoing theory to an important particular pair of congruences associated with a given surface. They are called the reciprocal congruences of Green.

## Surfaces with Doubly Stratifiable <br> Reciprocal Congruences

Let $S_{\mathbf{x}}$ be a surface on which the u-curve and the v-curve are the asymptotic curves on the surface. Then from (2.6), (2.7), (2.8) $S_{x}$ is an integral surface of the following pair of partial differential operations:

$$
\begin{align*}
& y_{u u}=\bar{\phi} x+\theta_{u} x_{u}+\beta x_{v} \\
& \mathbf{x}_{\mathrm{vv}}=\bar{q} \mathrm{x}+\gamma \mathrm{x}_{\mathrm{u}}+\theta_{\mathrm{v}} \mathrm{x}_{\mathrm{v}},  \tag{5.1}\\
& \theta=\log \beta \gamma,
\end{align*}
$$

with the following integrability conditions

$$
\begin{align*}
& \theta_{u v v}=(\gamma \varphi)_{u}+2 \bar{q}_{u}+\theta_{v} \theta_{u v}-\beta \gamma \psi \\
& \theta_{\mathrm{uuv}}=(\beta \psi)_{\mathrm{v}}+2 \bar{\phi}_{\mathrm{v}}+\theta_{\mathrm{u}} \theta_{\mathrm{uv}}-\beta \gamma \psi  \tag{5.2}\\
& \bar{\phi}_{\mathrm{vv}}-\theta_{\mathrm{v}} \bar{\phi}_{\mathrm{v}}+\beta \overline{\mathrm{q}}_{\mathrm{v}}+2 \overline{\mathrm{q}} \beta_{\mathrm{v}}=\bar{q}_{\mathrm{uu}}-\theta_{\mathrm{u}} \bar{q}_{\mathrm{u}}+\gamma \bar{\phi}_{\mathrm{u}}+2 \bar{\phi} \gamma_{\mathrm{u}}, \\
& \text { where } \varphi=\left(\log \beta \gamma^{2}\right)_{\mathrm{u}}, \quad \psi=\left(\log \beta^{2} \gamma\right)_{\mathrm{v}} . \tag{5.3}
\end{align*}
$$

We pause to define some terms that will be important in subsequent discussions.

First, the concept of a developable surface; it is the locus of the tangent lines of a curve. The tangents are the generators and the curve is the edge of regression of the developable.

It can be shown that s surface $S_{x}$ is a developable surface if, and only if,

$$
\mathrm{LN}-\mathrm{M}^{2}=0^{(1)}
$$

where L, M, N are defined in (2.4).
Second, the generators of a congruence can be assembled into a one-parameter family of developable surfaces in two ways. The lines of a congruence are the common tangents to two surfaces, called the focal surfaces of the congruence. The two points at which a generator touches the focal surfaces are called the focal points of the generator, and the tangent planes are the focal planes of the generator ${ }^{(2)}$

[^1]The method of obtaining these points and planes of the congruence will be indicated presently in this section.

On a surface $S_{x}$ referred to the asymptotic net on the surfaces, consider a point $P_{x}$ and a line 1 , thru $P_{x}$ but not lying in the tangent plane of $S_{\mathbf{x}}$ at $\mathrm{P}_{\mathbf{x}}$. Such a line may be determined by the points $\mathrm{P}_{\mathrm{x}}$ and $\mathrm{P}_{\mathrm{y}}$, where

$$
\begin{equation*}
y=x_{u v}-\bar{a} x_{u}-\bar{b} x_{v} \tag{5.4}
\end{equation*}
$$

where $\bar{a}$ and $\bar{b}$ are scalar functions of $u$ and $v$. The line 1 , at once determines another line $1_{2}$ - the polar reciprocal of $1_{1}$ with respect to the quadric of Lie at the point $\mathrm{P}_{\mathrm{x}}$. Referred to the tetrahedrom $\mathrm{P}_{\mathrm{x}}, \mathrm{P}_{\mathrm{x}_{\mathrm{u}}}, \mathrm{P}_{\mathrm{x}_{\mathrm{v}}}, \mathrm{P}_{\mathbf{x}_{\mathrm{uv}}}$ the equation of this quadric is

$$
\begin{equation*}
2\left(\mathrm{x}_{2} \mathrm{x}_{3}-\mathrm{x}_{1} \mathrm{x}_{4}\right)-\left(\beta \gamma+\theta_{\mathrm{uv}}\right) \mathrm{x}_{4}{ }^{2}=0 . \tag{5.5}
\end{equation*}
$$

The polar reciprocal of $1_{1}$ is the line $1_{2}$ which join $P_{\rho}$ and $P_{\sigma}$ where

$$
\begin{equation*}
\rho=\mathrm{x}_{\mathrm{u}}-\overline{\mathrm{b}}_{\mathrm{x}}, \quad \sigma=\mathrm{x}_{\mathrm{v}}-\overline{\mathrm{a}} \mathrm{x} \tag{5.6}
\end{equation*}
$$

As $u$ and $v$ vary, $1_{1}$ and $1_{2}$ generate two congruences $\Gamma_{1}$, and $\Gamma_{2}$ whose generators are in 1-1 correspondence.

Let us find the focal points of the generator 1 and the developables of $\Gamma_{1}$. Let $P_{z}$ be any point on $1_{1}$ were

$$
z=y+\lambda x .
$$

Let us determine $\lambda$ so that $P_{z}$ will be a focal point ${ }^{1}$. Let $C$ be a curve on $\mathrm{S}_{\mathrm{x}}$ passing thru $\mathrm{P}_{\mathrm{x}}$. If as $\mathrm{P}_{\mathrm{x}}$ varies C , generates a developable of $\mathrm{P}_{1}$ and if $\mathrm{P}_{z}$ is a focal point of $1_{1}$, then $\mathrm{P}_{z}$ will describe of curve of which $1_{1}$, is tangent at $P_{z}$. Then

$$
\frac{d z^{\prime}}{d t}=z_{u} \frac{d u}{d t}+z_{v} \frac{d u}{d t}
$$

must be a linear combination of $\mathbf{x}$ and y only. But we have

$$
\begin{aligned}
z_{u} & =\left(\bar{\phi}_{v}-\bar{a} \bar{p}+\beta \bar{q}+\lambda u\right) x+(A+\lambda) x_{u}+(F-2 \bar{a} \beta+\beta \varphi) x_{v} \\
- & \left(\bar{b}-\theta_{u}\right) y \\
z_{v} & =\left(\bar{q}_{u}-\bar{b} \bar{q}+\gamma \bar{\phi}+\lambda v\right) x+(G-2 \bar{b} \gamma+\gamma \psi) x_{u}+\left(\beta+x_{v}-\right. \\
& \left(\bar{a}-\theta_{v}\right) y
\end{aligned}
$$

where

$$
\begin{aligned}
& A=-\bar{a}_{u}-\bar{a} \bar{b}+\beta \gamma+\theta_{u v}, F=\bar{\phi}-\bar{b}_{u}+\bar{b} \theta_{u}-\bar{b}^{2}+\bar{a} \beta \\
& B=\bar{b}_{v}-\bar{a} \bar{b}+\beta \gamma+\theta_{u v}, G=\bar{q}-a_{v}-\bar{a} \theta_{v}-\bar{a}^{2}+\bar{b} \beta .
\end{aligned}
$$

Therefore

$$
\begin{aligned}
\frac{d z^{\prime}}{d t}=P x+ & Q y+\left[(A+\lambda) \frac{d u}{d t}+(G-2 \vec{b}+\gamma \varphi) \frac{d v}{d t}\right] x_{u} \\
& +\left[(p-2 \bar{a} \beta+\beta \varphi) \frac{d u}{d t}(\beta+\lambda) \frac{d v}{d t}\right] x_{v}
\end{aligned}
$$

where $P$ and $Q$ are functions we shall have no occasion to use. Hence $\frac{d z}{d t}$ is a linear combination of $x$ and $y$ if, and only if

$$
\begin{align*}
& (A+\lambda) d u+(G-2 \bar{b} \gamma+\gamma \psi) d v=0  \tag{5.8}\\
& (F-2 \bar{a} \beta+\beta \psi) d u+(\beta+\lambda) d v=0
\end{align*}
$$

Eliminating du and dv from these equations, we have:
or $\left|\begin{array}{ll}A+\lambda & \mathrm{F}-2 \bar{a} \beta+\beta \\ \mathrm{F}-2 \overline{\mathrm{a}} \beta+\beta \psi & \mathrm{B}+\lambda \\ \lambda^{2}+(\mathrm{A}+\mathrm{b}) \lambda+\mathrm{AB}-(\mathrm{F}-2 \bar{a} \beta+\beta \psi)\end{array}\right|=0$

If $\lambda_{1}$ and $\lambda_{2}$ are the roots of these quadratic equations then the points $\mathrm{P}_{\mathrm{z}_{1}}$ and $\mathrm{P}_{\mathrm{z}_{2}}$ where

$$
\mathrm{z}_{1}=\mathrm{y}+\lambda_{1} \mathrm{x}, \mathrm{z}_{2}=\mathrm{y}+\lambda_{2} \mathrm{x}
$$

are the focal points of $1_{1}$ and the surfaces $\mathrm{S}_{\mathrm{z}_{1}}$ nd $\mathrm{S}_{\mathrm{z}_{2}}$ are the focal surfaces of $\Gamma_{1}$.

If on the other hand we eliminate $\lambda$ from (5.8), we obtain

This is the differential equation of the curves in which the developables of $\Gamma_{1}$ intersect $S_{\mathbf{x}}$ which will be called the $\Gamma_{1}$-curves.

Since the equation is quadratic, the lines of the congruence can be assembled in two ways. Hence the line $1_{1}$ belongs to two different developables of $\Gamma_{1}$.

Let us similarly find the focal points and developables of $\Gamma_{2}$. The line $1_{2}$ which joins $\mathrm{P} \rho$ and $\mathrm{P} \sigma$ has a focal point at $\xi=\rho+\mu \sigma$ if

$$
\frac{\mathrm{d} \xi}{\mathrm{dt}}=\left(\rho_{\mathrm{u}}+\mu_{\mathrm{u}}+\mu \sigma_{\mathrm{u}}\right) \frac{\mathrm{du}}{\mathrm{dt}}+\left(\rho_{\mathrm{v}}+\mu_{\mathrm{v}} \sigma+\mu \sigma_{\mathrm{v}}\right) \mathrm{dv}
$$

is a linear combination of $\rho$ and $\sigma$ only. The values of $\rho_{\mathrm{u}}, \rho_{\mathrm{v}}, \sigma_{\mathrm{u}}$ and $\sigma_{v}$ are given by
$\rho_{\mathrm{u}}=\mathrm{Fx}-\left(\overline{\mathrm{b}}-\theta_{\mathrm{u}}\right) \rho+\beta \sigma, \rho_{\mathrm{v}}=\left(\overline{\mathrm{b}}_{\mathrm{v}}=+\overline{\mathrm{a}} \overline{\mathrm{b}}\right) \mathrm{x}-\overline{\mathrm{b}}+\mathrm{x}_{\mathrm{uv}}$
$\sigma_{\mathrm{u}}=\mathrm{Gx}+\gamma_{\rho}-\left(\overline{\mathrm{a}}-\theta_{\mathrm{v}}\right) \sigma, \sigma_{\mathrm{v}}=-\left(\overline{\mathrm{a}}_{\mathrm{u}}+\overline{\mathrm{a}} \overline{\mathrm{b}}\right) \mathrm{x}-\mathrm{a} \rho+\mathrm{x}_{\mathrm{uv}}$
Hence

$$
\begin{aligned}
\frac{d \xi}{d t}=P \rho+Q \sigma & +\left[F-\mu\left(\bar{a}_{u}+\bar{a} \bar{b}\right)\right] d u+\left[-\bar{b}_{v}-\bar{a} \bar{b}+\mu G\right] d v x \\
& +\left[\mu d_{u}+d_{v}\right] x_{u v}
\end{aligned}
$$

will be a linear combination of $\rho$ and $\sigma$ if, and only if

$$
\begin{gather*}
{\left[F-\mu\left(\bar{a}_{u}+\bar{a} \bar{b}\right)\right] d u+\left[-\bar{b}_{v}-\bar{a} \bar{b}+\mu G\right] d v=0} \\
\mu d u+d v=0 \tag{5.12}
\end{gather*}
$$

Eliminating du and $d v$, from (5.12), we have:

$$
\begin{array}{cc}
F-\mu\left(\bar{a}_{u}+\bar{a} \bar{b}\right)-\bar{b}_{v}-\bar{a} \bar{b}+\mu G \\
\mu & 1 \\
F+\left(\bar{b}_{v}-\bar{a}_{u}\right) \mu-G \mu^{2}=0
\end{array}
$$

If $\mu_{1}$ and $\mu_{2}$ are the roots of this quadratic then the focal points of $1_{2}$ are $P_{\xi 1}$ and $P_{\xi_{2}}$ where,

$$
\xi_{1}=\rho+\mu_{1} \sigma, \quad \xi_{2}=\rho+\mu_{2} \sigma
$$

and the loci of $P_{\xi_{1}}$ and $P_{\xi_{2}}$ are the focal surfaces of $\Gamma 2$.

Eliminating $\mu$, from (5.12) we have

$$
\begin{array}{cc}
\text { Fdu }-\left(\bar{b}_{v}+\bar{a} \bar{b}\right) d v-\left(\bar{a}_{u}+\bar{a} \bar{b}\right) d u+G d v \\
d v & =0
\end{array}
$$

or

$$
F d u^{2}-\left(\bar{b}_{v}-\bar{a} u\right) d u d v-G d v^{2}=0 .
$$

This is the differential equation of the curves in which the developables of $\Gamma_{2}$ cut the surface $S_{x}$. Since the equation is quadratic the developables of $\Gamma_{2}$ can be assembled in two ways.

We now raise a number of questions. Is it possible for $\Gamma_{1}$ and $\Gamma_{2}$ to be doubly stratifiable? What kind of surfaces sustain reciprocal congruences that are doubly stratifiable? What kind of reciprocal congruences, with respect to a surface, are doubly stratifiable?

To answer these questions let us first set up the system (3.2) for the pair $\Gamma_{1}$ and $\Gamma_{2}$. Here $\rho$ and $\sigma$ will replace $\overline{\underline{x}}$ and $\underline{y}$ in (3.2).

The Equations for $\Gamma_{1}$ and $\Gamma_{2}$

$$
\begin{array}{ll}
\mathrm{x}_{\mathrm{u}}=\mathrm{lx}+\mathrm{my}+\rho & \mathrm{y}_{\mathrm{u}}=\mathrm{ax}+\mathrm{by}+\mathrm{c} \rho+\mathrm{d} \sigma \\
\mathrm{x}_{\mathrm{v}}=\mathrm{l}^{\prime} \mathrm{x}+\mathrm{m}^{\prime} \mathrm{y}+\sigma & \mathrm{y}_{\mathrm{v}}=\mathrm{a}^{\prime} \mathrm{x}+\mathrm{b}^{\prime} \mathrm{y}+\mathrm{c}^{\prime} \rho+\mathrm{d}^{\prime} \sigma \\
\rho_{\mathrm{u}}=\mathrm{ex}+\mathrm{fy}+\mathrm{g} \rho+\mathrm{h} \sigma & \sigma_{\mathrm{u}}=\mathrm{px}+\mathrm{qy}+\mathrm{r} \rho+\mathrm{s} \sigma \\
\rho_{\mathrm{v}}=\mathrm{e}^{\prime} \mathrm{x}+\mathrm{f}^{\prime} \mathrm{y}+\mathrm{g}^{\prime} \rho+\mathrm{h}^{\prime} \sigma & \sigma_{\mathrm{v}}=\mathrm{p}^{\prime} \mathrm{x}+\mathrm{q}^{\prime} \mathrm{y}+\mathrm{r}^{\prime} \rho+\mathrm{s}^{\prime} \sigma
\end{array}
$$

where

$$
\begin{aligned}
& \mathrm{a}=\overline{\mathrm{p}}_{\mathrm{v}}+\beta \overline{\mathrm{q}}+\overline{\mathrm{b}} \theta_{\mathrm{uv}}+\overline{\mathrm{b}} \gamma \beta-\overline{\mathrm{a}} \overline{\mathrm{~b}}^{2}-\overline{\mathrm{a}}_{\mathrm{u}} \overline{\mathrm{~b}}+\overline{\mathrm{a}} \beta_{\mathrm{v}}+\overline{\mathrm{a}} \beta \theta_{\mathrm{v}}- \\
& \overline{\mathrm{a}} \beta-\overline{\mathrm{a}} \mathrm{~b}_{\mathrm{u}}-\overline{\mathrm{a}} \overline{\mathrm{~b}}^{2} \\
& \mathrm{a}^{\prime}=\overline{\mathrm{q}}_{\mathrm{u}}+\overline{\mathrm{p}} \gamma+\overline{\mathrm{b}} \gamma_{\mathrm{u}}+\overline{\mathrm{b}} \gamma \theta_{\mathrm{u}}-\overline{\mathrm{b}}^{2} \gamma+\overline{\mathrm{a}} \overline{\mathrm{~b}} \theta_{v}-\overline{\mathrm{a}}^{2} \overline{\mathrm{~b}} \\
& \mathrm{~b}=\theta_{\mathrm{u}}-\overline{\mathrm{b}}, \mathrm{c}=\theta_{\mathrm{uv}}+\beta \gamma-\overline{\mathrm{a}} \overline{\mathrm{~b}}-\overline{\mathrm{a}}_{\mathrm{u}}, \mathrm{~d}=\overline{\mathrm{p}}+\beta_{\mathrm{v}}+\beta \theta_{\mathrm{v}}- \\
& \bar{a} \beta-b_{u}+\bar{b} \theta_{u}-\bar{b}^{2} \\
& \mathrm{~b}^{\prime}=\theta_{\mathrm{v}}-\overline{\mathrm{a}}, \mathrm{c}^{\prime}=\overline{\mathrm{q}}+\gamma_{u}+\gamma \theta_{\mathrm{u}}-\overline{\mathrm{b}} \gamma+\overline{\mathrm{a}} \theta_{\mathrm{v}}-\mathrm{a}^{2}, \mathrm{~d}^{\prime}=\theta_{\mathrm{uv}}+ \\
& \beta \gamma-\overline{\mathrm{b}}_{\mathrm{v}}-\overline{\mathrm{a}} \overline{\mathrm{~b}} \\
& \mathrm{l}=\overline{\mathrm{b}}, \mathrm{~m}=0,1^{\prime}=\overline{\mathrm{a}}, \mathrm{~m}^{\prime}=0 \\
& \mathrm{e}=\mathrm{F}=\overline{\mathrm{p}}+\theta_{\mathrm{u}} \overline{\mathrm{~b}}+\overline{\mathrm{a}} \beta-\overline{\mathrm{b}}_{\mathrm{u}}-\overline{\mathrm{b}}_{2}, \mathrm{f}=0, \mathrm{~g}=\theta_{\mathrm{u}}-\overline{\mathrm{b}}, \mathrm{~h}=\beta \\
& e^{\prime}=\bar{a} \bar{b}-\bar{b} v, f^{\prime}=1, g^{\prime}=\bar{a}, h^{\prime}=0
\end{aligned}
$$

$$
\begin{aligned}
& \mathrm{p}=\overline{\mathrm{a}} \overline{\mathrm{~b}}-\overline{\mathrm{a}}_{\mathrm{u}}, \mathrm{q}=1, \mathrm{r}=0, \mathrm{~s}=\overline{\mathrm{b}} \\
& \mathrm{p}^{\prime}=\mathrm{G}=\overline{\mathrm{q}}-\overline{\mathrm{a}}_{\mathrm{v}}+\overline{\mathrm{b}} \gamma-\overline{\mathrm{a}}^{2}+\overline{\mathrm{a}} \beta_{\mathrm{v}}, \mathrm{q}^{\prime}=0, \mathrm{r}^{\prime}=\gamma, \mathrm{s}^{\prime}=\theta_{\mathrm{v}}-\mathrm{a}
\end{aligned}
$$

Imposing conditions (3.5) and (4.2) for double stratifiability we get:

$$
\begin{align*}
a_{u}^{\prime}+a^{\prime}\left(2 \bar{b}-\theta_{u}\right) & =a_{v}+a\left(2 \bar{a}-\theta_{v}\right) \\
\bar{a}_{u} & =\bar{b}_{v}=0 \\
\beta_{v} & =\beta\left(2 \bar{a}-\theta_{v}\right)  \tag{5.15}\\
\gamma_{u} & =\gamma\left(2 \bar{b}-\theta_{u}\right) \\
\bar{a}_{u} & +\bar{r}_{v}=\beta \gamma+\theta_{u v}
\end{align*}
$$

From the third and fourth of these equations, we obtain

$$
\begin{align*}
& \bar{a}=\frac{\beta_{v}+\theta_{u v}}{2 \beta}=\frac{\psi}{2} \\
& \bar{b}=\frac{\gamma_{u}+\theta_{u v}}{2 \gamma}=\frac{\psi}{2} \tag{5.16}
\end{align*}
$$

From (5.16) it follows that $1_{1}$ and $1_{2}$ are the directrices of Wilczynski and the congruences $\Gamma_{1}$ and $\Gamma_{2}$ are the directrix congruences of Wilczynski.

Inspection of (5.10), (5.14), the second equation of (5.15) and (5.16) shows that the developables of $\Gamma_{1}$ and $\Gamma_{2}$ correspond to the same conjugate net

$$
\begin{equation*}
F d u^{2}-G d v^{2}=0 \tag{5.17}
\end{equation*}
$$

on $\mathrm{S}_{\mathrm{x}}$.
From the second and last equation of (5.16), we obtain

$$
\begin{aligned}
& \overline{\mathrm{a}}_{\mathrm{u}}=\frac{\beta \gamma+\theta_{\mathrm{uv}}}{2} \\
& \overline{\mathrm{~b}}_{\mathrm{v}}=\frac{\beta \gamma+\theta_{\mathrm{uv}}}{2}
\end{aligned}
$$

But from (5.16) we have

$$
\begin{aligned}
& \bar{a}_{u}=\frac{1}{2}\left(\frac{\beta_{v}+\beta \theta_{v}}{\beta}\right)=\frac{1}{2}\left[(\log \beta)_{v u}+\theta_{v u}\right] \\
& \overline{\mathrm{b}}_{\mathrm{v}}=\frac{1}{2}\left(\frac{\gamma_{u}+\gamma \theta_{u}}{\gamma}\right) v=\frac{1}{2}\left[(\log \gamma)_{u v}+\theta_{u v}\right] .
\end{aligned}
$$

Hence $(\log \beta)_{u v}+\theta_{u v}=\beta \gamma+\theta_{u v}$

$$
(\log \gamma)_{\mathrm{uv}}+\theta_{\mathrm{uv}}=\beta \gamma+0_{\mathrm{uv}} .
$$

Consequently,

$$
\begin{align*}
& \frac{\partial_{2}}{\partial u \partial v}(\log \beta)=\beta \gamma  \tag{5.18}\\
& \frac{\partial^{2}}{\partial u \partial v}(\log \gamma)=\beta \gamma
\end{align*}
$$

Therefore,

$$
\begin{equation*}
\frac{\partial^{2}}{\partial u \partial v}\left(\log \frac{\beta}{\gamma}\right)=0 \tag{5.19}
\end{equation*}
$$

Equations (5.18) state that the asymptotic tangents of $\mathrm{SX}_{\mathrm{X}}$ belong to two linear complexes - the osculating linear complexes of the asymptotics.
The equations of these complexes cre

$$
\begin{align*}
& 2 w_{23}-\varphi w_{42}-\psi w_{34}=0  \tag{5.20}\\
& 2 w_{14}-\varphi w_{42}+\varphi w_{34}=\theta
\end{align*}
$$

They form a pencil of complexes whose directrix congruences are $\Gamma_{1}$ and $\Gamma_{2}$.

Consider the most general transformation which leaves the form of equations (5.1) invariant, namely

$$
\begin{equation*}
\mathrm{x}=\mathrm{c} \overline{\mathrm{x}}, \quad \bar{u}=\lambda(\mathrm{u}), \overline{\mathrm{v}}=\mu(\mathrm{v}), \mathrm{c} \text { const } \tag{5.21}
\end{equation*}
$$

where $\lambda$ ( $u$ ) is a function of $u$ alone and $\mu(v)$, a function of $v$ alone.
Then the new coefficients of (5.1) are given by

$$
\begin{gathered}
P=\frac{\bar{p}}{\lambda^{\prime 2}(u)}, Q=\frac{\bar{q}}{\mu^{2}(v)} \\
\beta=\beta \frac{\mu^{\prime}(v)}{\lambda^{\prime 2}(u)}, \gamma=\frac{\partial \lambda^{\prime}(u)}{\mu^{\prime 2}(v)} \\
\theta=\theta-\log \lambda^{\prime}(u) \mu^{\prime}(v) .
\end{gathered}
$$

It is also easy to show that $\theta=\log \bar{\beta} \bar{\gamma}$.

$$
\begin{equation*}
\frac{\beta}{\gamma}=\frac{V(v)}{U(u)} \tag{5.22}
\end{equation*}
$$

where $U(u)$ is an arbitrary function of $u$ alone and $V(v)$ is an arbitrary function of $v$ alone. Let us choose $\lambda(u)$ and $\mu(v)$ so that

$$
\frac{\bar{\beta}}{\bar{\gamma}}=1 .
$$

To do this, we note that,

$$
\frac{\bar{\beta}}{\bar{\gamma}}=\frac{\mu^{\prime 3}(v)}{\lambda^{\prime 3}(u)} \cdot \frac{\beta}{\gamma}=\frac{\mu^{\prime 3}(v)}{\lambda^{\prime 3}(v)} \cdot \frac{U(u)}{V(v)}
$$

Hence $\frac{\bar{\beta}}{\bar{\gamma}}=1$ if we choose $\lambda(u)$ and $\mu(v)$ so that

$$
\begin{aligned}
& \lambda^{\prime 3}(u) U(u)=k \\
& \mu^{3 \prime}(v) V(v)=k
\end{aligned}
$$

where $\mathrm{k} \neq 0$ may be taken equal to 1 . Then we may choose

$$
\lambda(u)=\frac{d u}{\sqrt{U(u)}}, \quad \mu(v)=\frac{d v}{\sqrt[3]{V(v)}}
$$

For this choice of $\lambda(u)$ and $\mu(v)$, the transformation (5.21) transforms the ratio $\frac{\beta}{\gamma}$ into

$$
\frac{\bar{\beta}}{\bar{\gamma}}=1 .
$$

Assuming that this transformation has been carried out we then have a system (5.1) in which $\beta=\mathrm{Y}$ and (5.18) becomes

$$
\begin{equation*}
\frac{\partial(\log \beta)}{\partial u \partial v}=\beta^{2} \tag{5.22}
\end{equation*}
$$

the general solution of which is

$$
\begin{equation*}
\beta=\frac{\sqrt{U^{\prime} v^{\prime}}}{(U+V)} \tag{5.23}
\end{equation*}
$$

where $U(u)$ and $V(v)$ are arbitrary functions of $u$ alone and $v$ alone respectively. Substituting $\beta=Y=\frac{\sqrt{U^{\prime} V^{\prime}}}{U+V}$ in the integrability conditions (5.2) and solving for $\bar{p}$ and $\bar{q}$, we get

$$
\begin{aligned}
& \overline{\mathrm{p}}=\frac{3}{2}\left(\frac{\sqrt{U^{\prime} V^{\prime}}}{U+V}\right)_{\mathrm{v}}-\frac{3}{4}\left(\frac{U^{\prime}}{U+V^{\prime}}\right)_{\mathrm{v}}+\mathrm{A}(\mathrm{u}) \\
& \overline{\mathrm{q}}=-\frac{3}{2}\left(\frac{\sqrt{U^{\prime} V^{\prime}}}{U+V}\right)_{u}-\frac{3}{4}\left(\frac{V^{\prime}}{U+V}\right)_{u}+3(v)
\end{aligned}
$$

where $A(u)$ and $B(v)$ are arbitrary functions.
By (5.16), (5.23) and (5.24) the functions $\beta, \overline{\mathrm{p}}, \overline{\mathrm{q}}, \overline{\mathrm{a}}$ and $\overline{\mathrm{b}}$ have been computed to satisfy all integrability conditions (5.15)
except the first. These five functions $\beta, \overline{\mathrm{p}}, \overline{\mathrm{q}} \overline{\mathrm{a}}$ and $\overline{\mathrm{b}}$ depend on four arbitrary functions $U(u), V(v), A(u)$ and $B(v)$. If these four arbitrary functions are now chosen so that the two remaining conditions - the last equation of (5.2) and the first equation of (5.15) - are satisfied, then the five functions $\beta, \overline{\mathrm{p}}, \overline{\mathrm{q}}, \overline{\mathrm{a}}$ and $\overline{\mathrm{b}}$ determine a surface $S_{x}$ which sustain a doubly stratifiable pair of reciprocal congruences $\Gamma_{1}$ and $\Gamma_{2}$. Since there are four functions to be chosen and only two equations to satisfy, the choice of the arbitrary set $U(u), V(v), A(u), B(v)$ can, clearly, be made in an infinite number of ways.

We now recapitulate the foregoing results in the following theorem.

Theorem. There is an infinite number of surfaces which sustain a pair of doubly stratifiable reciprocal congruences. These congruences are the directrix congruences of Wilczynski whose developables correspond on the surface to the same conjugate net. The asymptotic tangents of the surface belong to the linear complexes which give rise to the directrix congruences of Wilczynski.

We now consider a particular solution $\beta=\frac{1}{u+\mathrm{v}}$ of (5.22) which leads to an interesting result.
6. The solution $\beta=\gamma=\frac{1}{u+v}$

The particular solution

$$
\begin{equation*}
\beta=\frac{1}{u+v} \tag{6.1}
\end{equation*}
$$

of the equation

$$
\frac{\partial^{2}(\log \beta)}{\partial_{u} \partial_{\mathrm{v}}}=\beta^{2}
$$

gives $\quad \overline{\mathrm{p}}=\overline{\mathrm{q}}=\frac{9}{4} \beta^{2}$

$$
\begin{equation*}
\overline{\mathrm{a}}=\overline{\mathrm{b}}=\frac{3}{2} \beta . \tag{6.2}
\end{equation*}
$$

The equations (5.1) and (5.14) of the developables $\Gamma_{1}$ and $\Gamma_{2}$ are satisfied identically. Hence the developables are indeterminate.

The line $l_{1}$ of $\Gamma_{1}$ is now determined by the points $P_{x}$ and $P_{y}$ where

$$
y=x_{u v}+\left(\frac{3}{2} \beta\right) x_{u}+\left(\frac{3}{2} \beta\right) x_{v}
$$

The point $P_{z}$, where

$$
\begin{gathered}
\mathrm{z}=\mathrm{y}+\left(\frac{3}{4} \beta^{2}\right) \mathrm{x}=\left(\frac{3}{4} \beta^{2}\right) \mathrm{x}+\left(\frac{3}{2} \beta\right) \mathrm{x}_{\mathrm{u}}+\left(\frac{3}{2} \beta\right) \mathrm{x}_{\mathrm{v}} \\
+\mathrm{x}_{\mathrm{uv}}
\end{gathered}
$$

lies on $1_{1}$; its coordinates, referred to the tetrahedron ( $\mathrm{P}_{\mathrm{x}}, \mathrm{P}_{\mathrm{xu}}, \mathrm{P}_{\mathrm{xv}}, \mathrm{P}_{\mathrm{x}_{\text {uv }}}$ ),
are:

$$
\begin{equation*}
\mathrm{kx}_{1}=\frac{3}{4} \beta^{2}, \mathrm{kx}_{2}=\frac{3}{2} \beta, \mathrm{kx}_{3}=\frac{3}{2} \beta, \mathrm{kx}_{4}=1 . \tag{6.3}
\end{equation*}
$$

The line $1_{2}$ of $\Gamma_{2}$ is determined by $\mathrm{P}_{\rho}$ and $\mathrm{P}_{\sigma}$, where

$$
\rho=\mathrm{x}_{\mathrm{u}}+\left(\frac{3}{2} \beta\right) \mathrm{x}, \sigma=\mathrm{x}_{\mathrm{v}}+\left(\frac{3}{2} \beta\right) \mathrm{x} .
$$

Referred to the same tetrahedron, the coordinates of $\mathrm{P}_{\rho}$ and $\mathrm{P}_{\sigma}$ are

$$
\left(\frac{3}{2} \beta, 1,0,0\right),\left(\frac{3}{2} \beta, 0,1,0\right) .
$$

Obviously $\mathrm{P}_{\rho}$ and $\mathrm{P}_{\sigma}$ lie in the plane $\pi$ whose equation is:

$$
\begin{equation*}
\pi: x_{1}-\left(\frac{3 \beta}{2}\right) x_{2}-\left(\frac{3 \beta}{2}\right) x_{3}+\left(\frac{15 \beta^{2}}{4}\right) x_{4}=0 . \tag{6.4}
\end{equation*}
$$

Therefore the line $l_{2}$ also lies in this plane whose coordinates are

$$
\begin{equation*}
\mathrm{k} \xi_{1}=1, \mathrm{k} \xi_{2}=\frac{-3}{2} \beta, \mathrm{k} \xi_{3}=\frac{-3 \beta}{2}, \mathrm{k} \xi_{4}=\frac{15 \beta^{2}}{4} . \tag{6.5}
\end{equation*}
$$

From (6.3) it follows that $\mathrm{P}_{\mathrm{z}}$ lies in the plane $\pi$; that is $1_{1}$ pierces the plane $\pi$ at $P_{z}$. This makes $\pi$ and $\mathrm{P}_{\mathrm{z}}$ united in position. If in (6.3) we eliminate k and $\beta$ homogeneously, we have

$$
\begin{equation*}
3 x_{1} x_{4}-x_{2} x_{3}=0 \tag{6.6}
\end{equation*}
$$

which is quadric.
Similarly, from (6.5) we obtain

$$
\begin{equation*}
3 \xi_{1} \xi_{4}-5 \xi_{2} \xi_{3}=0 \tag{6.7}
\end{equation*}
$$

whose point equation is

$$
\begin{equation*}
5 x_{1} x_{4}-3 x_{2} x_{3}=0 \tag{6.8}
\end{equation*}
$$

which is another quadric.
Both quadrics (6.6) and (6.8) contain the points $\mathrm{P}_{\mathrm{x}}, \mathrm{P}_{\mathrm{x}_{\mathrm{u}}}$, $\mathrm{P}_{\mathrm{x}_{\mathrm{v}}}, \mathrm{P}_{\mathrm{x}_{\mathrm{uv}}}$ and both are non-degenerate. The properties of these quadrics will be investigated in another paper which will deal with the surfaces of the congruences.


[^0]:    (1) E. J. Wilczynski, Projective Differential Geometry of Curved Surfaces, I Trans. of the Am. Math. Society 8, 233-60.

[^1]:    (1) Lane, p. 38
    (2) Ibid, p. 82

